

Uncertainty estimation for *in situ* measurement procedures, including the sampling component

Prof. Michael H Ramsey

Chair of Eurachem UFS Working Group

School of Life Sciences,

University of Sussex, Brighton, UK

m.h.ramsey@sussex.ac.uk

ISS Workshop on UFS
9-10th March 2023, Rome
30 minutes + discussion

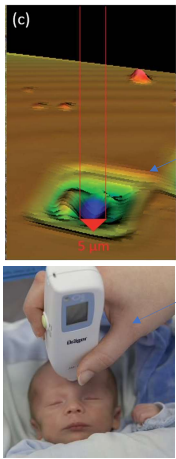


Overview

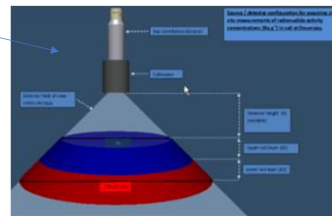
- What is an *in situ* measurement method?
- Why is Measurement Uncertainty (MU) important?
- Advantages/Disadvantages of *in situ* measurement methods¹
- Estimation of MU for *in situ* measurements + Case Study
- Judging Fitness-for-Purpose (FFP) of *in situ* measurements
 - hence Validation of Measurement Procedures (Including Sampling)
 - For two different purposes
 1. Compliance with regulation
 2. Geochemical Mapping
- Conclusions

1. Ramsey M.H. (2020) Challenges for the estimation of uncertainty of measurements made *in situ*. Accreditation and Quality Assurance: Journal for Quality, Comparability and Reliability in Chemical Measurement. 26(4), 183-192. 2020. <https://doi.org/10.1007/s00769-020-01446-4>

What are *in situ* measurements?



- Taken *in situ* without disturbing or removing the test material
 - Different from 'on site' measurements, where physical sample is removed, measured locally
 - Sampling indivisible part of measurement process, e.g.
- Soils - handheld portable (P)XRF for some metals
- Minerals – SIMS at micron scale (e.g. Oxygen isotopes)
- Gases - many sensors – how most measurements are made!
 - e.g. Photolionisation detectors for VOCs, (e.g. benzene), IR for CH₄, CO₂
- Liquids - e.g. pH, UV-Vis for NO₃, TOC, H₂S
- Clinical - Transcutaneous Bilirubinometer (TcB) – jaundice ?
- Radioactivity – passive γ -ray detection of ¹³⁷Cs in very large sample mass (200 – 1000kg)



Advantages of *in situ* measurement methods

1. Measurement result virtually instantaneous (versus days/weeks for lab)
 - saving lives in clinical sector
 - saving money in commercial & environmental sectors
 - enables sensing networks to monitor analyte variability across time or space
2. Substantially lower cost, even if MU higher, enables:
 - taking of many more 'samples' - 1000 less exact measurements provide more information than 100 more exact = giving better coverage of target in space and/or time
 - Even 100% coverage – e.g. groundhog (γ -ray spec)
3. No sample preparation
 - avoid loss of analyte by removing, storing, & preparing sample
 - eliminating costs of taking, storing and disposing of samples
4. Ability to quantify heterogeneity of test material (U_{HET})
5. Can be made by less skilled personnel? – really a disadvantage –
 - *In situ* measurement scientists need to be more skilled
 - able to take most appropriate samples (of the 'undisturbed' kind) in real world
 - & take measurements of acceptable quality, both without local supervision



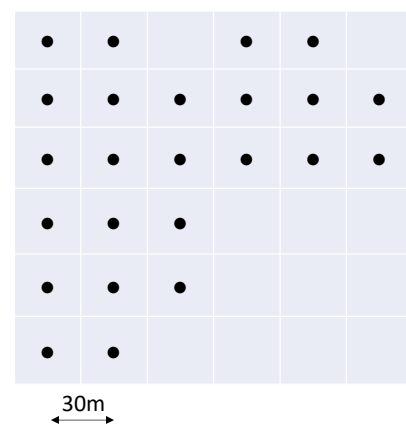
Disadvantages of *in situ* measurements

- *In situ* measurements often have larger uncertainty (MU)
 - Due partially to heterogeneity of analyte concentration (not mixed)
 - Vertical heterogeneity in test portion + critical penetration depth (e.g. PXRF)
 - Detection limits often not as low as for *ex situ* measurements
- However, MU can be estimated by duplicate method (or SPT)
 - Can judge whether Measurements are fit-for-purpose (FFP) - if UfS quantified

Case Study: Estimation of UfS & MU for measurements made *in situ*



Site of a medieval Pb smelter at Wirksworth, Derbyshire, UK
Hand-held portable x-ray fluorescence spectrometer (PXRF)
used to measure Pb concentration [Pb] in topsoil *in situ**

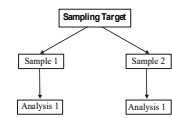


Grid of 24 sampling
targets used to survey
[Pb] across site

*Ramsey M.H. (2020) Measurement Uncertainty from Sampling: Implication for Testing, Diagnostics and Inspection. Presented to 17th IMEKO TC 10 and EUROLAB Virtual Conference "Global Trends in Testing, Diagnostics & Inspection for 2030" October 20-22, 2020. <https://www.imeko.org/publications/tc10-2020/IMEKO-TC10-2020-042.pdf>

Case Study: Estimation of U_{fS} & MU for measurements made *in situ* (Method)

- Duplicate Method used to estimate random components of MU of *in situ* measurements
 - as repeatability
- Equivalent of ‘duplicate samples’ are taken by placing the *in situ* measurement device twice, reflecting two independent interpretations of measurement protocol.
- In this study PXRF duplicates were 2m apart, in a randomly chosen direction, to reflect uncertainty in location



- These two sampling points are both equally likely interpretations of the protocol given that particular surveying technology
- **Simplified design** used for speed (no analytical duplicates)

Duplicated PXRF measurements – for random component of U_{fS} (Results)

Target Number	S1Pb mg/kg	S2Pb mg/kg
1	1005	1633
2	4631	3723
3	1415	2264
4	865	1350
5	2899	2216
6	721	1758
7	2122	1014
8	1321	1043
9	3348	3904
10	11543	5570
11	2904	2833
12	2617	2762
13	976	786
14	6127	3874
15	331	576
16	12878	8948
17	3246	4332
18	9006	6098
19	1936	1989
20	5811	6289
21	4611	2880
22	1326	1442
23	1215	2713
24	2070	2305

- Duplicated ‘samples’ show quite large variation (from small scale heterogeneity)
 - RANOVA3 gave a robust estimate of MU (U'_{meas}) = 55%
 - Robust statistical methods much less susceptible to small proportion of outlying values (i.e. < 10%), which are evident in some duplicates (e.g. Targets 10 & 18).
- Need external estimate of $U'_{analysis} = 3\%$.
 - Made using additional *ex situ* PXRF measurements (made in lab on prepared versions of removed samples from same 24 targets), in fully balanced experimental design (i.e. with duplicated analyses)
 - Assumes instrumental performance of PXRF similar *in situ* to *ex situ*
- Gives $U'_{sampling, in situ} = 54.9\% = (\sqrt{55^2 - 3^2})$, using.... $s_{sampling} = \sqrt{s_{meas}^2 - s_{analytical}^2}$
 - Sampling causes 99.7% of MU
- Any underestimate of $U'_{analysis}$ (as repeatability) has little effect on value of MU
- More generally, PXRF instrument reports uncertainty (U') of around 3%, but..
- **Actual MU is much higher at ~ 55 %** - when U_{fS} included
- Better expressed as **Uncertainty Factor $^FU = 1.85$**
 - due log-normal distribution (explained later)

Ufs Estimation using RANOVA3

Data input area

ID	Analys1	Analys2	Analys3	Analys4
B11	1005	1005	1633	1633
B12	4631	4631	3723	3723
B13	1415	1415	2264	2264
B14	865	865	1350	1350
B15	2899	2899	2216	2216
B16	721	721	1758	1758
B21	2122	2122	1014	1014
B22	1321	1321	1043	1043
B23	3348	3348	3904	3904
B24	11543	11543	5570	5570
B25	2904	2904	2833	2833
B26	2617	2617	2762	2762
B32	976	976	786	786
B33	6127	6127	3874	3874
B34	331	331	576	576
B35	12878	12878	8948	8948
B44	3246	3246	4332	4332
B45	9006	9006	6098	6098
B46	1936	1936	1989	1989
B54	5811	5811	6289	6289
B55	4611	4611	2880	2880
B56	1326	1326	1442	1442
B64	1215	1215	2713	2713
B65	2070	2070	2305	2305

Classical ANOVA				Robust ANOVA			
BALANCED DESIGN				BALANCED DESIGN			
Mean	2778.5	No. Targets	24	Mean	2856.6	No. Targets	24
Total Sdev	2797.3			Total Sdev	2050		
Standard deviation	2494.8	Btn Target	1265.1	Standard deviation	1893.5	Sampling	785.61
% of total variance	79.55	Analysis	0	% of total variance	85.31	Analysis	0
Expanded relative uncertainty (95%)	77.25	Measure	785.61	Expanded relative uncertainty (95%)	55.00	Measure	785.61
Uncertainty Factor (95%)	1.8514			Uncertainty Factor (95%)	1.8514		

Classical ANOVA			
Mean	3275.5	No. Targets	24
Total Sdev	2797.3		
Standard deviation	2494.8	Btn Target	1265.1
% of total variance	79.55	Sampling	20.45
Expanded relative uncertainty (95%)	77.25	Analysis	0.00
Uncertainty Factor (95%)	1.8514	Measure	20.45

Repeat S1A1 as S1A2, to use software for balanced design

Expressing MU as Uncertainty Factor (F_U)

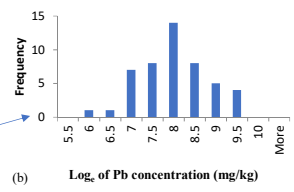
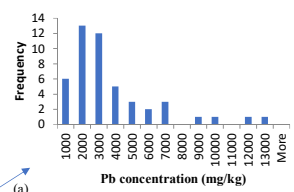
- MU better expressed as an **Uncertainty Factor (F_U)** as MU is large ($U'_{meas} > 40\%$) (UFS Guide ([2], p21,48)

$$F_U = \exp(2s_{G,meas})$$

- Where, $s_{G,meas}$ is the the equivalent of s_{meas}
 - calculated within RANOVA3 as natural logarithms of measurement values
 - $s_{G,meas}$ is 0.308 for Case Study

$$F_U = \exp(2 * 0.308) = 1.85$$

- LCL and UCL then calculated as x/F_U and $x * F_U$, respectively
- Large MU often due to frequency distribution being log-normal
 - i.e. positively skewed - rather than normal (i.e. Gaussian)
- For Case Study distribution of PXRf measurements is log-normal
 - Made ~normal by taking logarithms of all measurement values

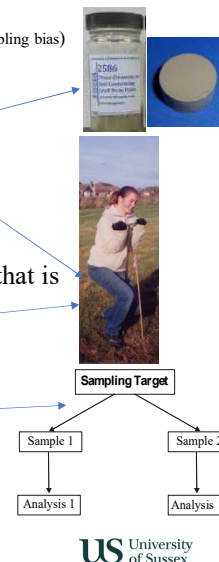


Estimation of UFS (and MU) for measurements made *in situ* (Include Analytical Bias)

- Systematic component of MU of *in situ* measurements from analytical bias (not sampling bias)
 - estimated by measurements made on matrix-matched CRMs (e.g. NIST 2710), but...
 - unlike most test materials in real world

CRM	Dried	Ground	Homogenized	Compacted
Test material	Moist	Unground	Heterogeneous	Un-consolidated

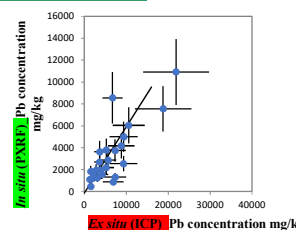
- To overcome this mis-match, compare *in situ* against *ex situ* measurements
 - made for same analyte on same sampling targets
- Need to also match value of the ‘measurand’, which is effectively the true value that is being estimated
 - i.e. total Pb concentration in dry soil
- In Case Study, also removed *ex situ* samples taken at same locations as PXRF measurement made
 - Also with simplified balanced design (i.e. without Analysis 2)
 - for all 24 sampling targets, but 8 targets would be OK for routine investigation
 - dry, disaggregate, sieve (<2mm), grind and acid digestion in a remote laboratory (i.e. *ex situ*)
 - then analysed by ICP-AES (traceable to CRMs)



‘Bias’ of *in situ* PXRF against *ex situ* ICP-AES measurements

Target ID	Ex situ ICP-AES	SD ICP (35.8%)	In situ PXRF	SD PXRF (27.5%)
A6	7340	2628	1319	363
A5	8815	3156	4177	1149
A4	1522	545	1840	506
A3	1290	462	1108	305
A2	9340	3344	2547	700
A1	3080	1103	1240	341
B6	4180	1496	1568	431
B5	1926	690	1183	325
B4	3670	1314	3626	997
B3	6718	2405	8555	2353
B2	5630	2016	2869	789
B1	3630	1300	2690	740
C5	6880	2463	881	242
C4	9370	3354	5002	1376
C3	1522	545	454	125
C2	21877	7832	10919	3003
D3	5230	1872	3788	1042
D2	18784	6725	7556	2078
D1	2800	1002	1963	540
E3	10584	3789	6050	1664
E2	7316	2619	3745	1030
E1	2235	800	1384	381
F3	3860	1382	1964	540
F2	5210	1865	2188	602

- Systematic component of MU estimated as bias...
 - by comparing average value of both *in situ* PXRF measurements
 - against *ex situ* ICP-AES measurement
- Relationship modelled as a function of concentration -
 - Using FREML (Functional Relationship Estimation by Maximum likelihood [1, 2])
- In FREML uncertainty of both variables properly taken into account.
 - Also possible to use ordinary least-squares regression, but this can only allow for uncertainty in y-axis (e.g. PXRF) and ignores uncertainty for x-axis (e.g. ICP-AES)



$$\text{Model} \rightarrow [\text{Pb}]_{in\ situ} = b(1) \times [\text{Pb}]_{ex\ situ} + b(0)$$

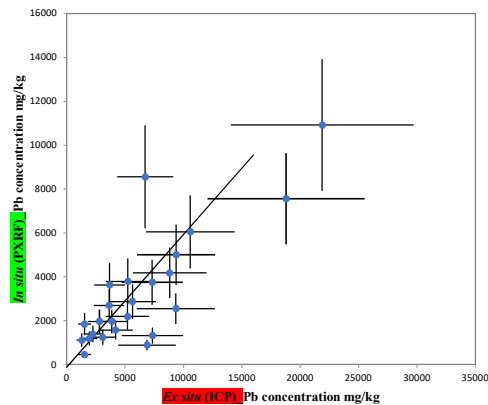
- Slope coefficient of linear model (b(1)) → rotational component of bias
- Intercept coefficient b(0) → translational component

[1] AMC Software, downloaded gratis from: <https://www.rsc.org/Membership/Networking/InterestGroups/Analytical/AMC/Software/>
 [2] Analytical Methods Committee (2002) Fitting a linear functional relationship to data with error on both variables, Technical Brief No.10, Royal Society of Chemistry, London

'Bias' of *in situ* PXRF against *ex situ* ICP-AES measurements (2)

Equation describing relationship, showing both coefficients and their standard errors (in parentheses):

$$[Pb]_{in\ situ} = 0.60 (\pm 0.09) \times [Pb]_{ex\ situ} - 120 (\pm 288)$$



- Estimated rotational bias of *in situ* PXRF measurements
 - compared against the *ex situ* ICP measurements
 - calculated from slope coefficient, is **-40%** ($\pm 9\%$)
 - i.e. $100 \times (1 - 0.60)$.
- No translational bias detected, as..
 - intercept coefficient = -120 mg/kg (± 288)
 - not statistically different from zero
- Possible causes of measurement bias identified as:
 - soil moisture
 - Material/particles > 2mm diameter (removed for *ex situ* sample)
 - surface roughness in the PXRF 'undisturbed sample'
 - Depth difference between undisturbed sample for *in situ* PXRF (~1mm) and removed *ex situ* field sample for ICP-AES (150 mm) [1]

[1] Argyraki, A., Ramsey, M.H. and Potts P.J. (1997) Evaluation of portable XRF for in-situ measurements of lead on contaminated land. Analyst 122, 743-749

US University of Sussex

Treatment of Systematic component of MU for *in situ* measurements - Option 1

Option 1 - 'correct' *in situ* measurements ($[Pb]_{PXRF,corr}$) to agree with *ex situ* values by applying a rearrangement of the bias model

- omitting the non-significant intercept for this Case Study

$$[Pb]_{PXRF,corr} = \frac{[Pb]_{PXRF,raw} - b(0)}{b(1)} = \frac{[Pb]_{PXRF,raw}}{0.60}$$

Uncertainty of correction (*se'* bias) = 0.09, as < 0.2, can be:-

Combined (as relative percentage 9%), into MU value $U' = 55\%$ ($u' = 27.5\%$)

([1], all expressed as relative standard uncertainty)

$$u'_{corr} = \sqrt{(u'^2 + (se'_{b(1)})^2)}$$

$$u'_{corr} = \sqrt{(27.5^2 + 9^2)} = 28.9\%$$

$$U'_{corr} = 57.9\%$$

- slightly up from 55%

[1] by approach described in UFS Guide, Section A2/6.4).

US University of Sussex

Treatment of Systematic component of MU for *in situ* measurements - Option 1b

Option 1b - 'correct' when MU is expressed as Uncertainty Factor:

FU , expressed as $s_{G,meas}$,

- using an approximation [1]

$$s_{G,meas,corr} = \sqrt{s_{G,meas}^2 + (s'_{bias})^2}$$

Expanded uncertainty factor FU of **1.85** increases slightly to **1.88**

using Equation

$$^FU = \exp(2s_{G,meas})$$

[1] Ramsey M H and Ellison S L R (2017) Combined uncertainty factor for sampling and analysis. Accreditation and Quality Assurance, 22(4), 187-189 DOI 10.1007/s00769-017-1271-y

Treatment of Systematic component of MU for *in situ* measurements - Option 2

Option 2 is not to correct, but to add the entire bias, and its uncertainty, to MU [2]

- again all terms expressed as relative percentage.

$$u'_{corr} = \sqrt{(u'^2 + ((b(1) - 1)^2) + (se_{b(1)}^2)}$$

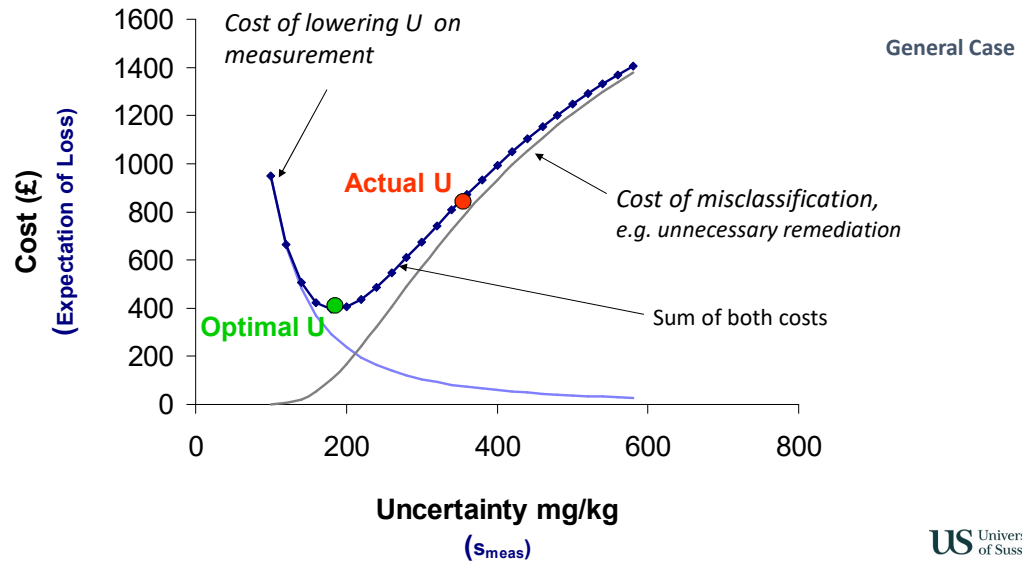
-
- For this case study:

$$u'_{corr} = \sqrt{(27.5^2 + 40^2 + 9^2)} = 49\%$$

$$U'_{corr} = 98\%$$

[1] Ramsey M H and Ellison S L R (2017) Combined uncertainty factor for sampling and analysis. Accreditation and Quality Assurance, 22(4), 187-189 DOI 10.1007/s00769-017-1271-y
[2] UFS Guide, Section A2/6.4 page 56

Judging FFP of *in situ* measurements – using Optimal U hence validation of measurement methods (including sampling)



Judging FFP using Optimized Uncertainty (OU) equation

$$E(L) = C [1 - \Phi(\epsilon_1 / s_{\text{meas}})] + D/s_{\text{meas}}^2$$

$E(L)$ – expectation of financial loss (= Total Cost)

s_{meas} – measurement uncertainty

Φ – standard normal cumulative distribution function

ϵ_1 – error limit = $|T - c|$

(T = threshold value, c = contaminant concentration at which to optimise)

D – combined optimal cost for sampling and analysis

C – consequence costs (e.g. potential losses resulting from misclassification)

Thompson M, Fearn T (1996) What exactly is fitness for purpose in analytical measurement? Analyst, 121, 275–278.

Ramsey M.H., Taylor P.D. and Lee J.C. (2002) Optimized contaminated land investigation at minimum overall cost to achieve fitness-for-purpose, Journal of Environmental Monitoring, 4, 5, 809 – 814.

Input data for Optimised MU

for *in situ* measurements

For Case Study

Item	Value	Units	U'
Sampling cost (each)	29	£	
Analytical cost (each)	12	£	
Consequent cost per location, for false positive classification (i.e. unnecessary remediation)	10000	£	
U_{sampling}	784	mg kg ⁻¹	54.9%
$U_{\text{analytical}}$	43	mg kg ⁻¹	3%
$U_{\text{measurement}}$	786	mg kg ⁻¹	55%
Threshold value of concentration	2000	mg kg ⁻¹	
Concentration at which to optimise	2020	mg kg ⁻¹	

Also use individual cost (& MU) of Sampling and Analysis

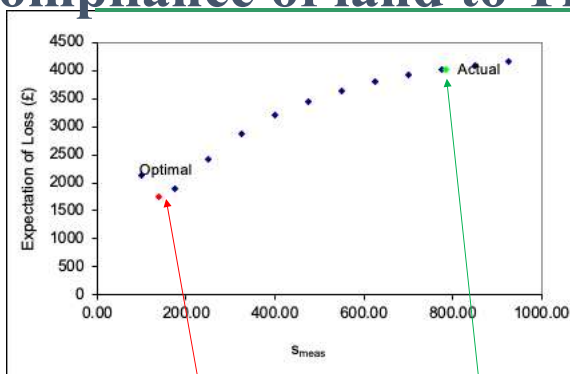
- to calculate which is more cost effective to reduce overall MU

For 30m grid spacing

- From ANOVA + external u_{anal}

- UK limit at time of survey

FFP of *in situ* measurements? – Purpose 1: Compliance of land to Threshold (2000 mg kg⁻¹)



Optimal
uncertainty
138 mg kg⁻¹
£2286

Actual
uncertainty
786 mg kg⁻¹
£4,026

In situ procedure currently **not Fitness-for-Purpose** (FFP)

- for classifying Pb against threshold (T) of 2000 mg kg⁻¹
- Because Actual U is >> than Optimal U

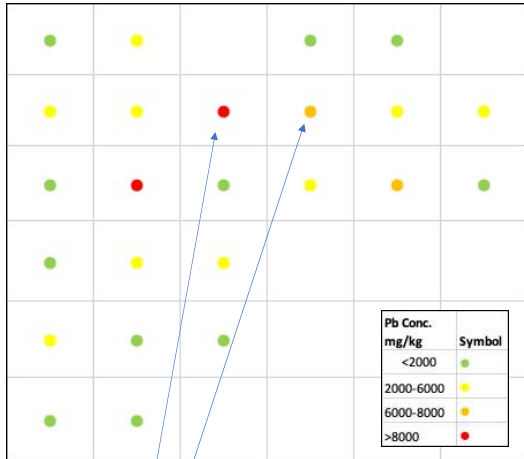
- To achieve FFP, need to:-
- Reduce MU x 5.7 (= 786/138) to achieve FFP
 - MU is 99.7% UfS (from ANOVA), so
- Reduce UfS x 5.8 to achieve FFP
 - Would require 34-fold composite measurement at each location (5.8²) – impractical

- To approach FFP:-

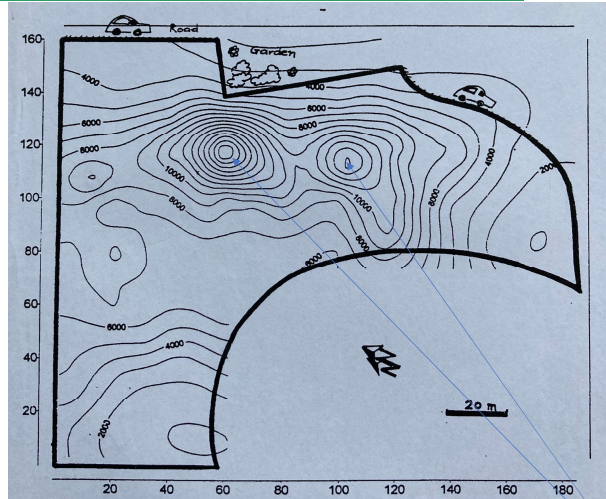
- Low cost of *in situ* allows closer grid spacing (e.g. 10m)
- Hence 9x lower remediation cost
 - gives 14x lower consequence costs (£278) at same MU ^[1]

[1] Taylor P D, Ramsey M H and Potts P.J. (2004) Balancing measurement uncertainty against financial benefits: a comparison of *in situ* and *ex situ* analysis of contaminated land. Environmental Science and Technology 38, 6824-6831.

FFP of *in situ* measurements? – Purpose 2: In situ measurements for Geochemical Mapping - FFP?



Map of 24 Pb concentrations (mg kg^{-1}) measured by PRXF showing two 'hot spots' of high [Pb] [1]



Contour Map of modelled Pb concentration (mg kg^{-1}) based on 159 other measurements from several surveys, showing two clear peaks due to Pb smelters [1]

[1] Argyraki A (1997) Estimation of measurement uncertainty in the sampling of contaminated land. PhD Thesis, Imperial College, University of London

Alternative Purpose of *in situ* measurements?

- **Geochemical mapping** has a different FFP criterion
- Second FFP criterion that MU should not contribute $> 20\%$ of total variance [1]
- Target $u_{meas} = 917 \text{ mg kg}^{-1}$ ($= 20\%$ of total variance $= \text{SQRT}(0.2 \cdot 2050^2)$)
- Actual (robust estimate) $u_{meas} = 786 \text{ mg kg}^{-1}$ (ANOVA2 output)
- $786 < 917 \text{ mg kg}^{-1}$ indicates that **measurement results** (& therefore **measurement procedure**)
- **are fit for that purpose**
- Same conclusion FFP when Expressed In terms of relative uncertainty
- Actual robust MU of 55% $<$ Target MU of 64%
- But 'Target' MU is more a preferred **maximum value** than a rigorous target
- i.e. Actual MU $<$ Target MU is not a deficiency
- **Even lower Actual MU beneficial** as it would further improve reliability of geochemical map
- So *in situ* PXRF does give broadly reliable geochemical map of Pb for this site
- Can approximately locate location of Pb smelters



[1] UfS Guide, Section 16.2

Conclusions

- *In situ* measurement methods are useful, but have MU including UfS
- MU (inc UfS) can be estimated using the Duplicate Method
 - but systematic effects requires the use of an *ex situ* method for validation*
- Judging Fitness-for-Purpose (FFP) of *in situ* measurements
 - enabled Validation of measurement methods (including sampling)
 - Against whatever purpose is specified
 - Using a particular FFP criterion (e.g. either Optimal MU, or % of total variance)
- Case study *in situ* PXRF (for Pb at one particular site) proved to be:
 - FFP for Geochemical Mapping
 - But not FFP for Compliance with regulation (at relevant threshold)